



Design and manufacturing of plastic injection mould

09 – Ejection system

The role of ejection system

- Cause of shrinkage the product will suit tightly to the core
- Demoulding of the part from the mould

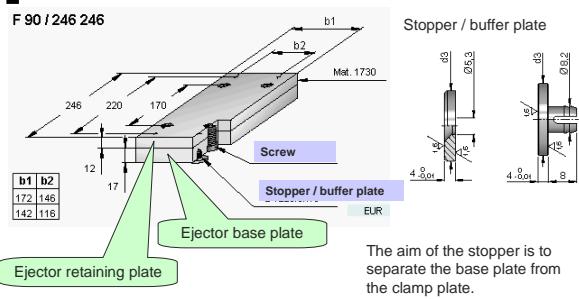
2

Location of the ejection

- Close to the critical areas
- So large area as it can
- The deformation of the part is forbidden
- Aesthetical viewpoint (the mark of the ejection bar)

3

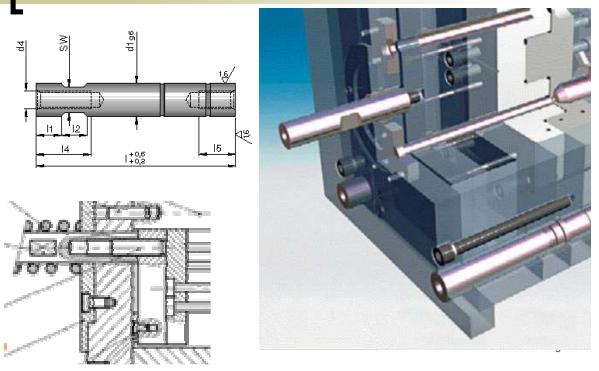
Ejector plates



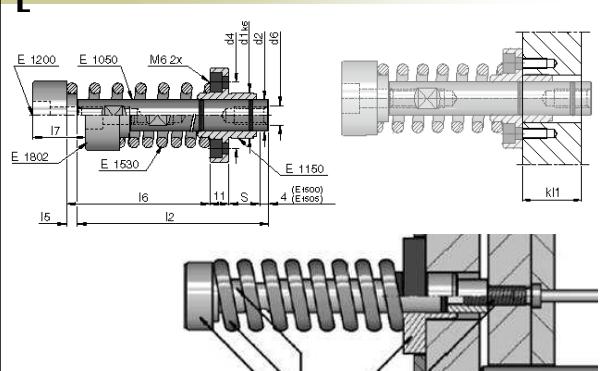
The aim of the stopper is to separate the base plate from the clamp plate.

4

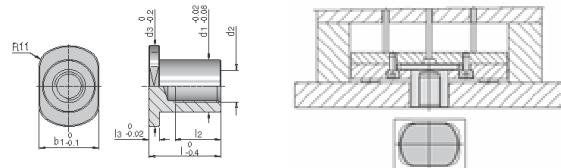
Moving of the ejection plates



Moving of the ejection plates



Moving of the ejection plates

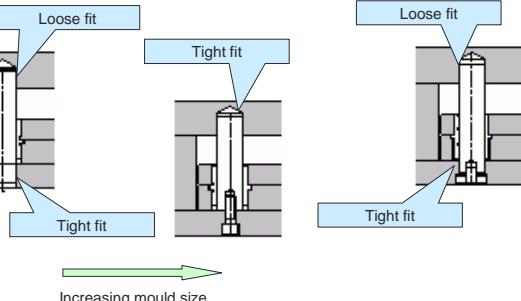


The suggested length of the thread is $1.5 - 2 \times d$.

This insert ensures this requirement.

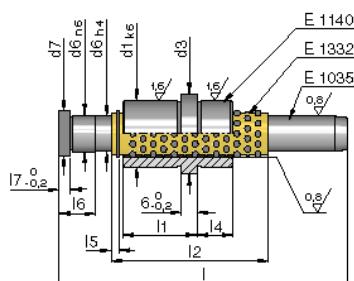
7

Guide of the ejection plates



8

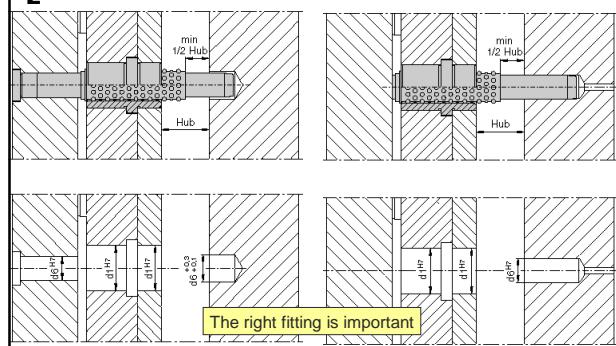
Guide of the ejection plates



Ball-roll guide bush

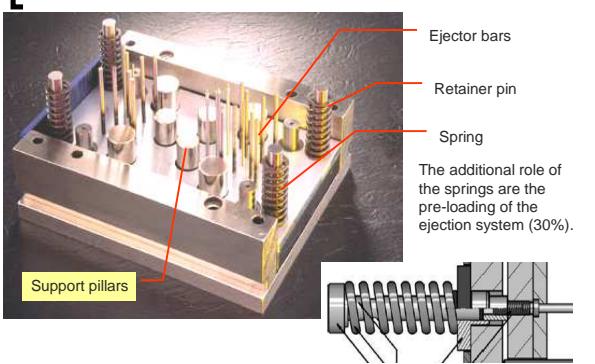
9

Guide of the ejection plates

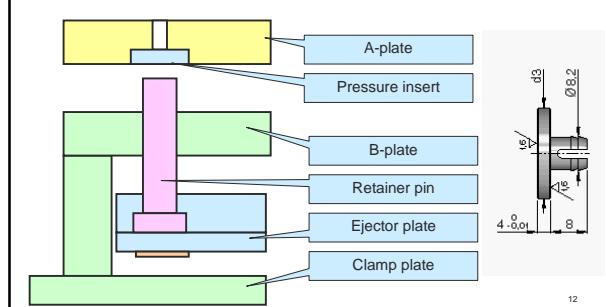


The right fitting is important

Re-moving of the ejection plates

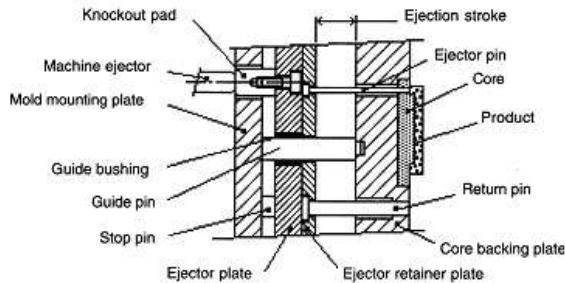


Retainer pin



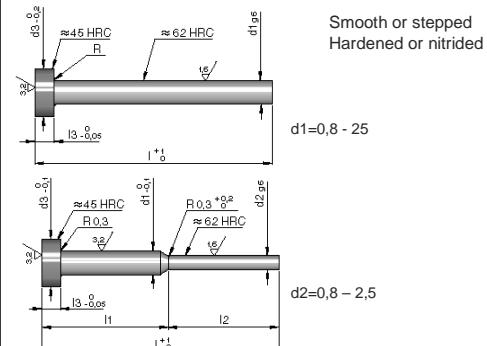
12

Summary



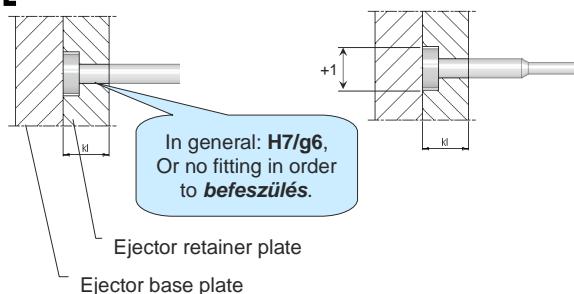
13

Cylindrical ejector pin



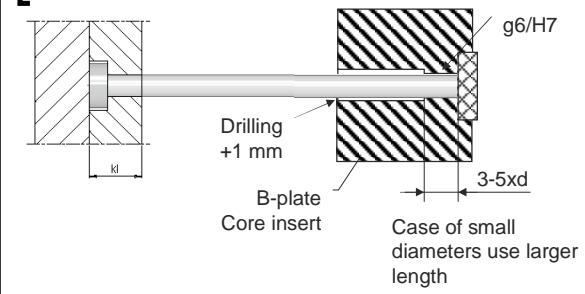
14

Fit in the ejector retainer plate



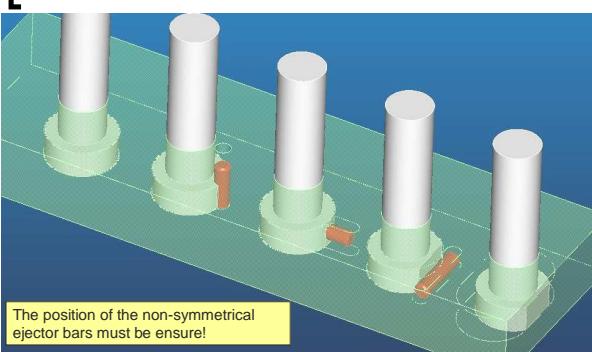
15

Guide in the B plate or core insert

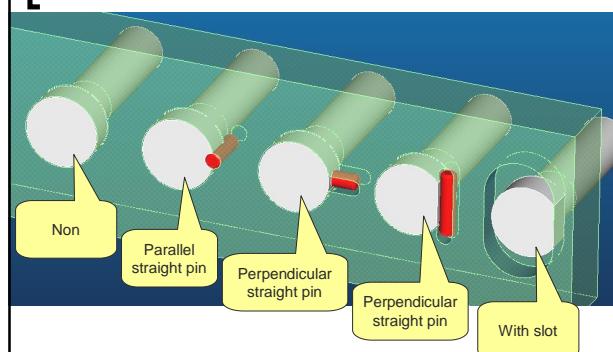


16

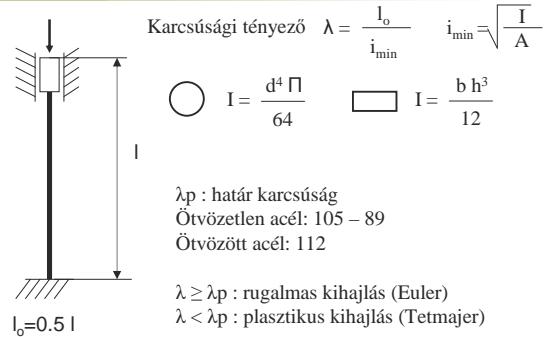
Ensure the angle position



Ensure the angle position



Kihajlási veszély



19

Kihajlás

Rugalmas kihajlás:

$$\text{Törőfeszültség: } \sigma_t = \frac{\Pi^2 E}{\lambda^2} \quad \lambda = \frac{l_o}{i_{min}} \quad i_{min} = \sqrt{\frac{I}{A}}$$

$$F_t = \sigma_t A \Rightarrow F_t = \Pi^2 \frac{I_{min} E}{l_o^2}$$

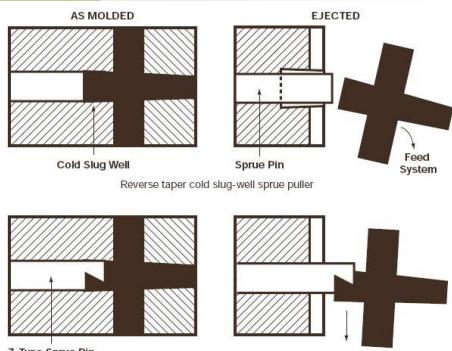
$$F_{meg} = \frac{F_t}{b} \quad b: 2 - 5 \text{ (karcsúsággal növekszik)}$$

Képlékeny kihajlás:

$$\text{Törőfeszültség: } \sigma_t = 303 - 1.29 \lambda \quad (\text{ötvözött acél esetén})$$

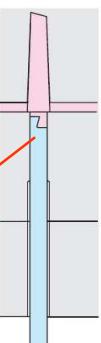
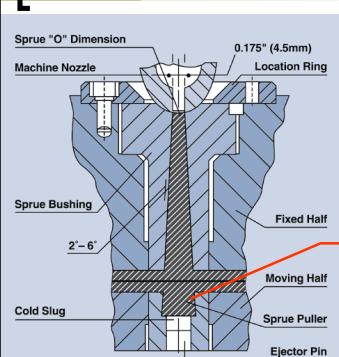
20

Sprue puller

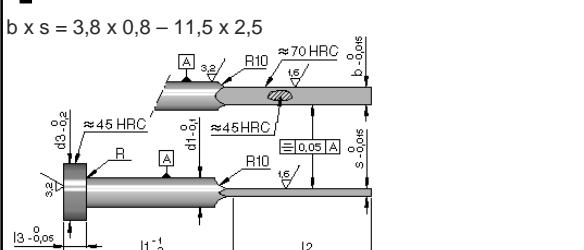


21

Sprue puller

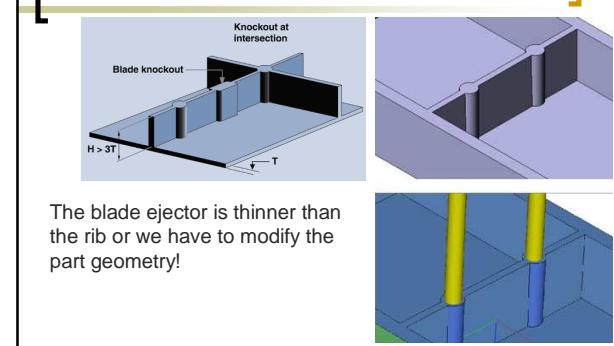


Rectangular / blade ejector pin



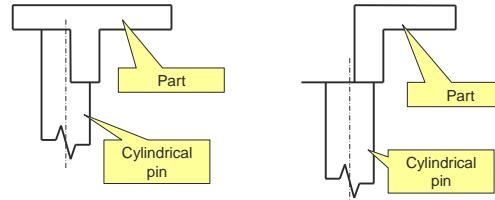
23

Ejection on the rib



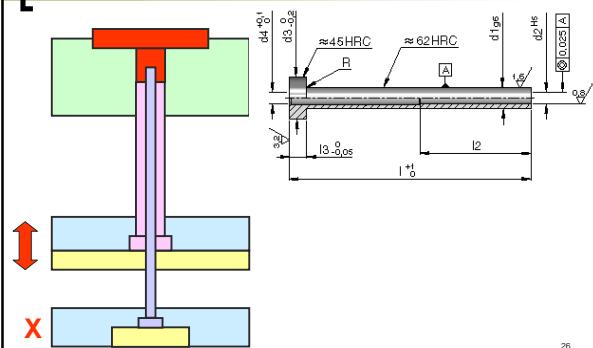
24

Ejection n the rib



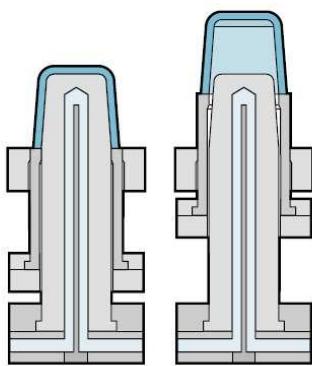
25

Sleeve ejector



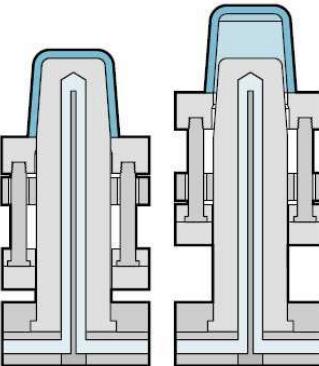
26

Ejector bush



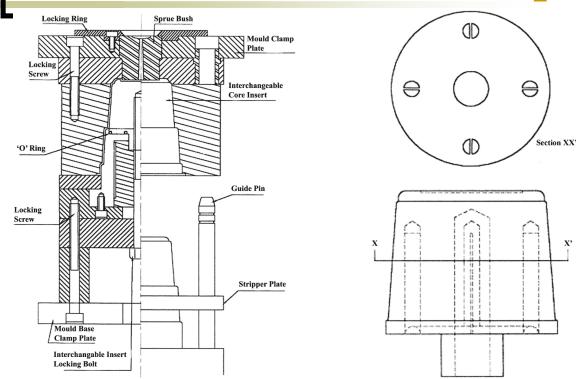
27

Stripper plate

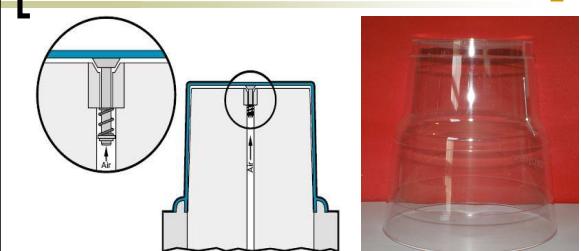


28

Stripper plate



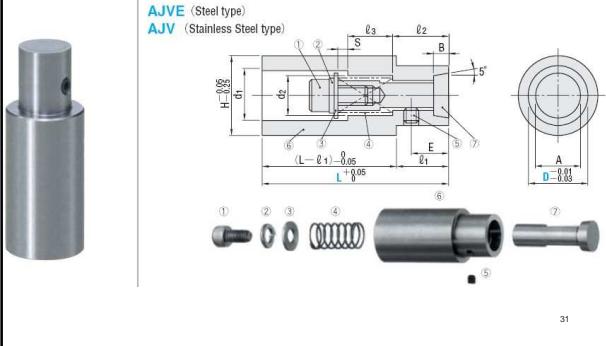
Ejection by air



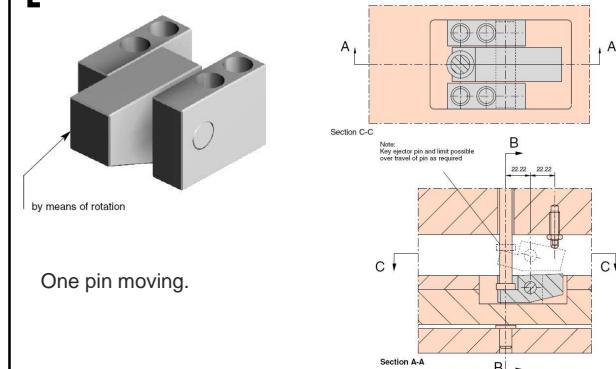
Thick wall.

30

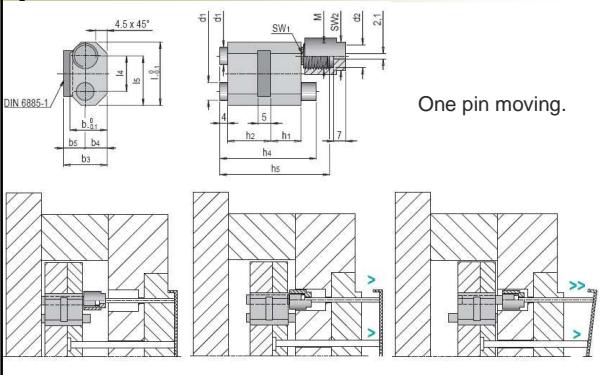
Air valve for ejection



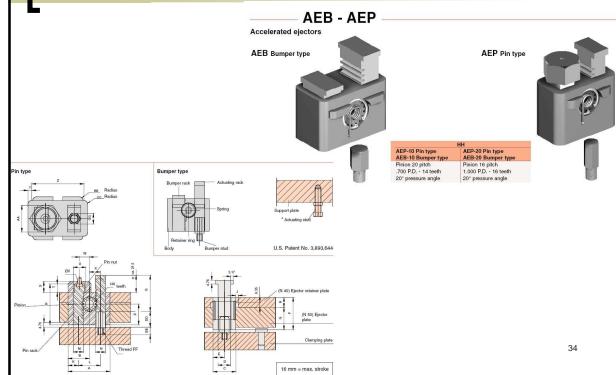
Two steps ejection



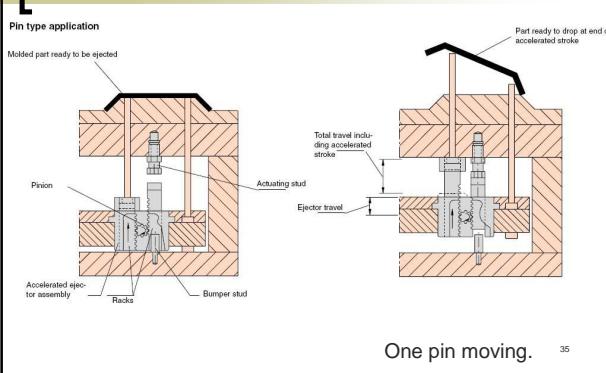
Two steps ejection



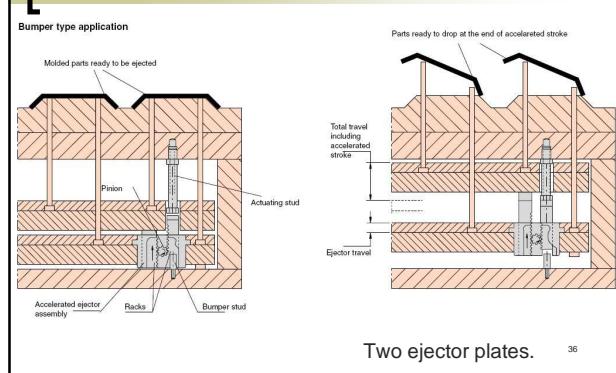
Two steps ejection



Two steps ejection

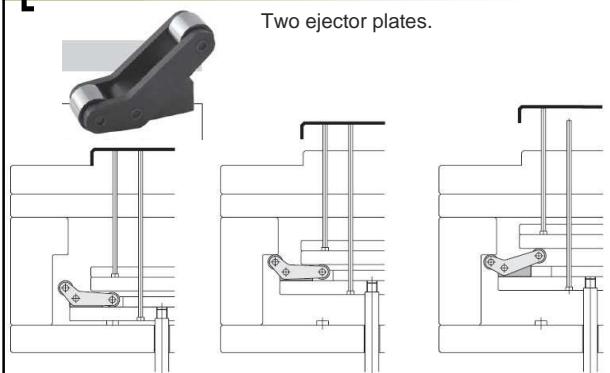


Two steps ejection

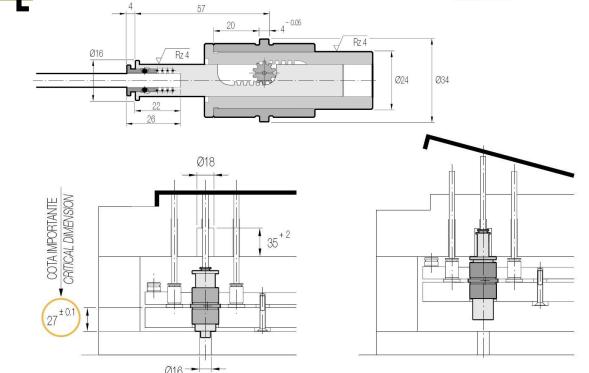


Two steps ejection

Two ejector plates.



Two steps ejection

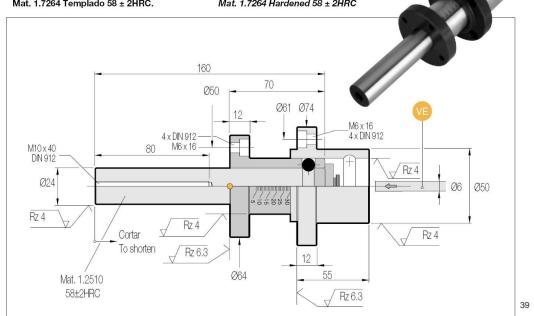


Two steps ejection

DOBLE EXPULSION / DOUBLE EJECTION

Mat. 1.7264 Templado 58 ± 2HRC.

Mat. 1.7264 Hardened 58 ± 2HRC

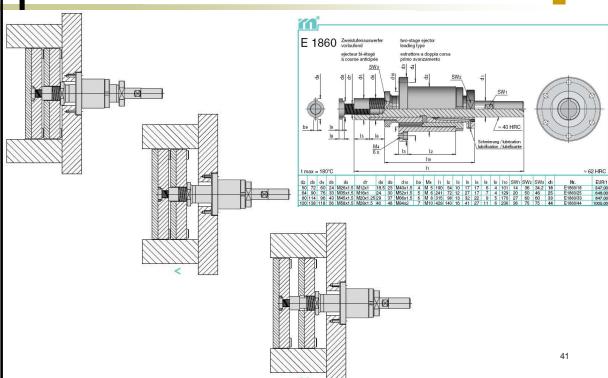


Two steps ejection

Si selecciona 20...
If 20 is selected...
obtiene un 1º recorrido de 20 milímetros...
20 millimeters 1st stroke is obtained...
y un 2º recorrido libre
and a free 2nd stroke

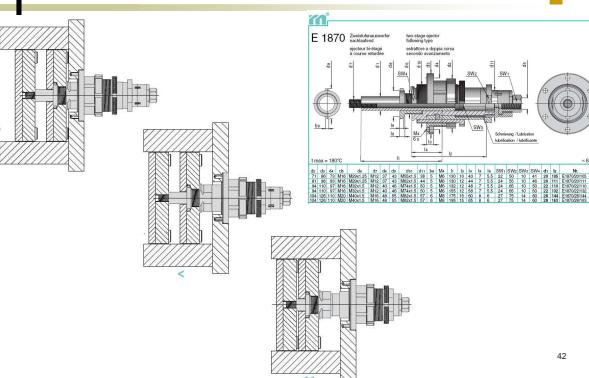
40

Two steps ejection



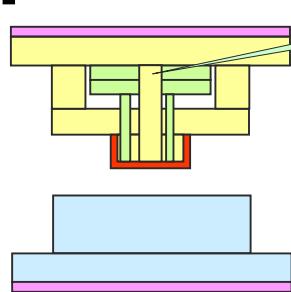
41

Two steps ejection



42

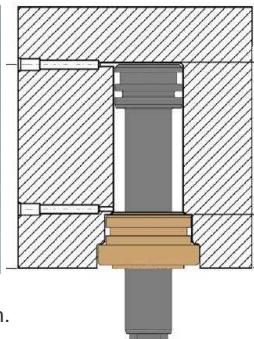
Ejection in the A-side



- Moving/Drive:
 - Spring
 - Hydraulic cylinder
 - From the B-side

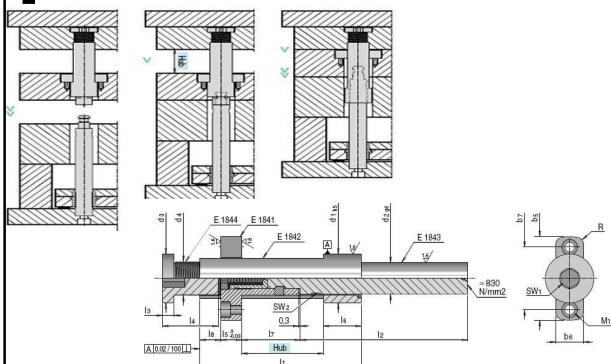
43

Moving by hydraulic cylinder

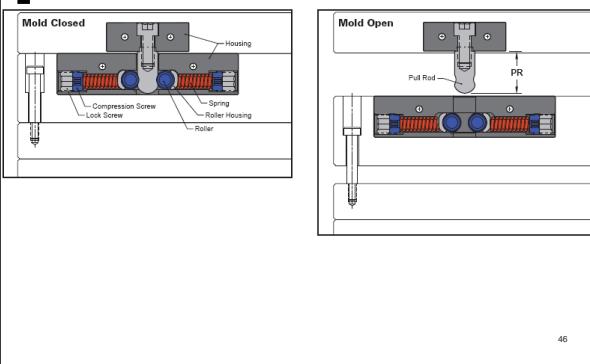


In-mould-cylinder hydraulic system.

Round latch lock

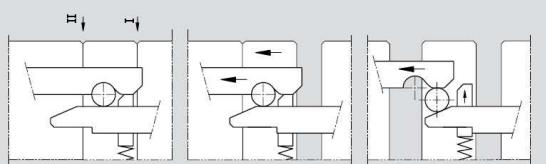


Spring lock system



46

Latch locking unit

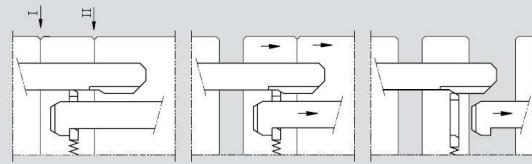


Z170/1

Mat.: 1.2764



Latch locking unit

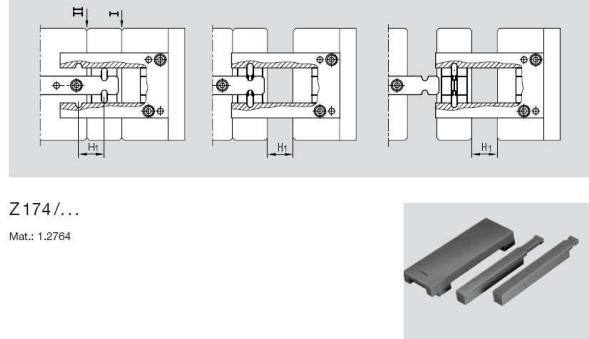


Z171/1

Mat.: 1.2764



Latch locking unit



Examples

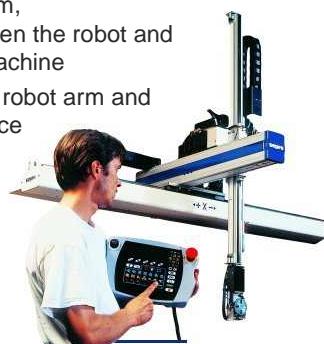


Strack animation films

50

Robotic demoulding

- Install the robot system, communication between the robot and the injection mould machine
- Enough space for the robot arm and appropriate part surface
- Robot gripper



Industrial robot

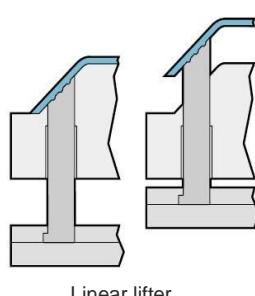
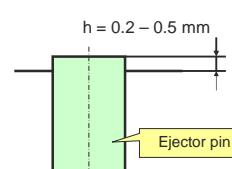


- Mechanical fitting
- Connect the controllers
- Robot programming

52

Grip the part

- Put up from the cavity
 - Ensure the part position
- Linear lifter
 - Put up and hold



53

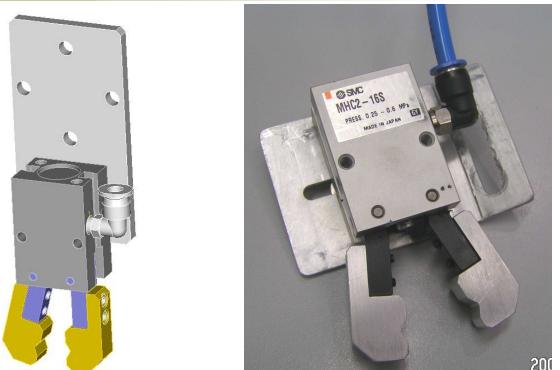
Robot gripper

- Mechanical (pneumatic)
- Vacuum



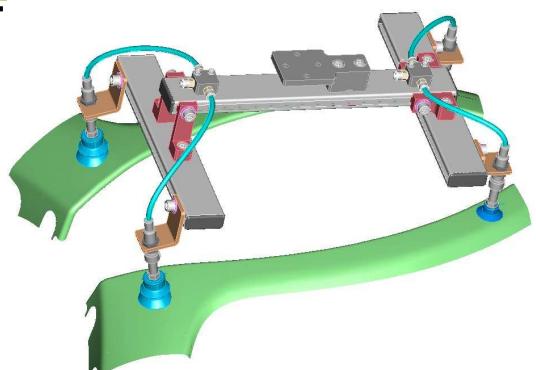
54

Mechanical gripper



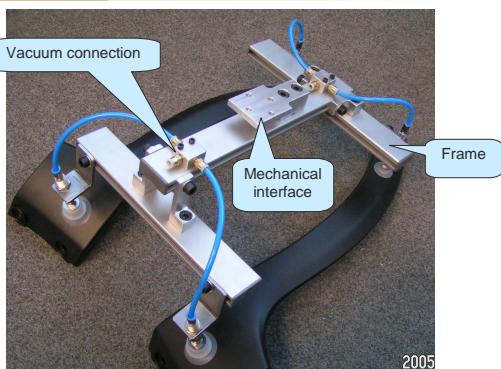
200

Vacuum gripper



5

Vacuum gripper



2005

57

Vacuum gripper

